

Australian Centre for Space Engineering Research (ACSER)

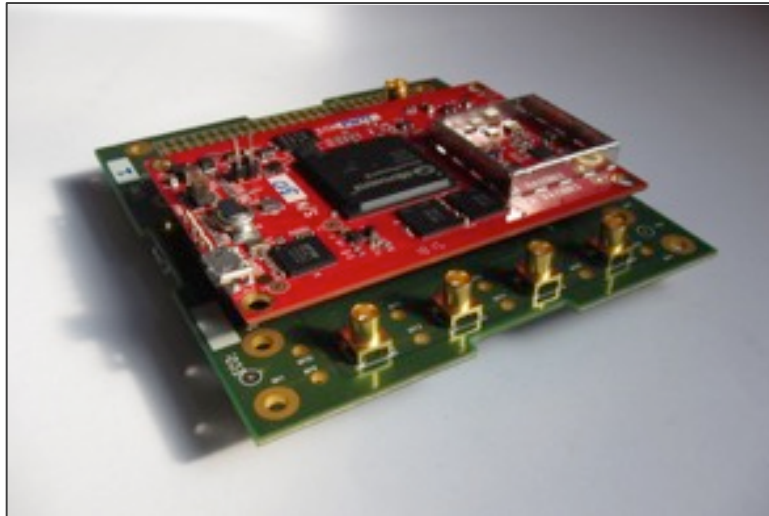
# An ANZ GPS Receiver for ANZ Cubesats and Launches

Presented by

**Eamonn Glennon**

at

**Cubesat2017, 19-20 April 2017, UNSW Sydney**



# Australian & New Zealand GPS Heritage

- Namuru FPGA based GPS receivers in development since 2003
- Developed by General Dynamics Ltd (NZ), UNSW's ACSER & SNAP Lab, and Embedded GNSS Pty Ltd
- Kea V4.1SB hardware suited for CalPoly Cubesat standard, Namuru V32R3A suited for Boeing Colony 2 designs
- Firmware capable of autonomous in-orbit operation (acquisition, tracking, navigation and timing) and high-G acceleration (suitable for launch)
- Namuru V32R3A flying on DST Group Biarri (Point & Squad)
- Kea V41SB flying on DST Group Buccaneer Risk Mitigation Mission, UNSW EC0 QB50 and USyd Inspire2 QB50 cubesats

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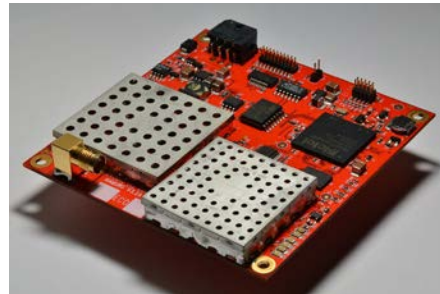
# Selected Past Receiver Designs



Namuru V1

Namuru V2R4

Namuru DLR



Namuru V32R3A

# Kea V4.1SB Receiver Module

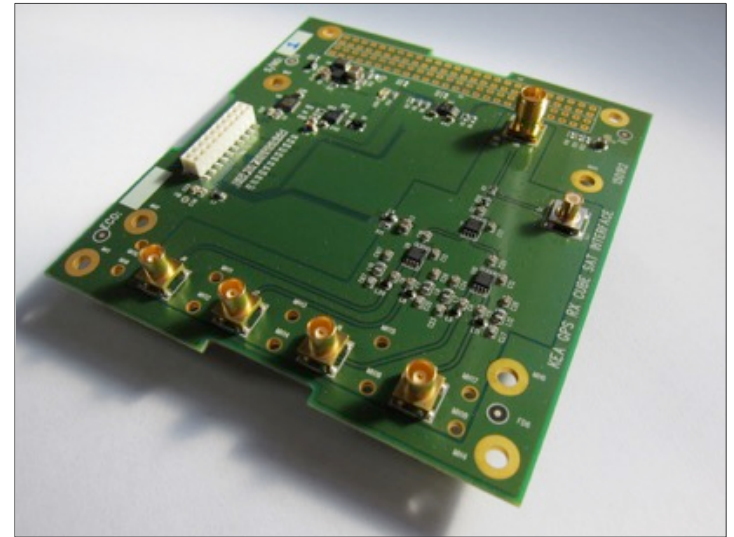
- Hardware design developed/owned by General Dynamics Ltd (NZ) and marketed through Kea GNSS Pty Ltd (NZ)
- Credit card sized
- SmartFusion2 SOC
  - Large flash based FPGA with 50k or 80k logic elements and enhanced SEU immunity
  - Powerful 166 MHz ARM Cortex M3 processor
- 512 Mb of SECDED LPDDR SDRAM
- 8 MB of serial Flash
- 8 kB of FRAM (ferromagnetic RAM)
- CMOS RF ASIC capable of L1/E1 operation
- Super-capacitor powered RTC
- Support for disciplined VC-TCXO and reference frequency output
- USB2 interface for debugging and data-capture



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# CalPoly CubeSat Interface Board

- Hardware design developed/owned by General Dynamics Ltd (NZ) and marketed/sold through Kea GNSS Pty Ltd (NZ)
- Convert credit-card sized Kea to CalPoly form-factor
- Different interface boards for different customers
- Support includes:
  - PC104/CalPoly Cubesat bus interface
  - USB UART serial port interface
  - GPS antenna switching



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# Aquarius GPS Firmware

- C code developed/owned by Eamonn Glennon since Namuru V1 (2004)
- Fully licensed to UNSW
- Features
  - Simple RTOS with tasks, signals, semaphores, timers; recently ported to FreeRTOS
  - GPS driver API for frequency plan portability (GP2015, BL2627)
  - Carrier smoothing
  - VC-TCXO Syntonization ( $\pm 10$  ppb)
  - Synchronization ( $< \pm 20$  ns, 95%)
  - 1 Hz carrier phase output for L1 carrier phase precise navigation
  - NMEA inspired commands and reports
  - QZSS capable, 1 channel allocated to QZSS
  - Adaptions for operation in LEO, including  $\pm 40$  kHz frequency search, orbit aware Kalman filter, TLE aided warm start, high dynamics, respectable tracking sensitivity
- Ported to Altera NIOS-2 and ARM Cortex M3 (~160 kB)

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# FPGA Correlator IP

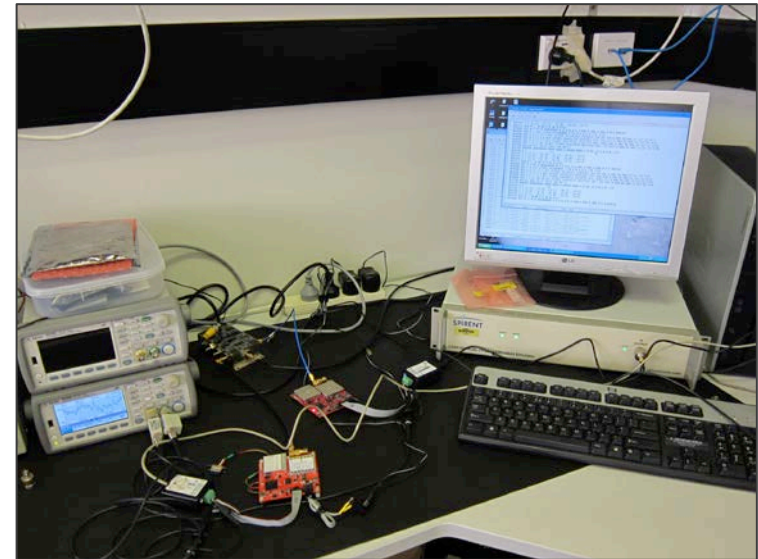
- Two sets of IP developed/owned by UNSW
- Multi-channel GPS correlator design based on the Zarlink 2021 design
  - Typically instantiated with 11 or more correlator channels
  - Ported to Altera Cyclone FPGAs, Microsemi SmartFusion2 SoCs and Microsemi ProASIC3E FPGAs
  - 3 (ProASIC) to 4 (SF2) code phase taps,  $\frac{1}{2}$  chip separation
  - Timing pulse output circuitry
- A Delay Doppler Map Accelerator (DDMA) hardware block used to calculate DDMs for GPS-Reflectometry
  - Ported to MicroSemi SmartFusion and SmartFusion2 SoCs
  - Size of DDMA depends on FPGA memory resources

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# Spirent Simulations

- Spirent simulation performed to test for LEO operation and multi-stage launch to orbit
- LEO accuracy is shown in WGS84 ECEF coordinates
- Rocket launch accuracy is shown in the radial, along and cross-track dimensions
- Rocket launch dynamics
  - Up to 40 m/s/s of acceleration in this scenario (tracking loops expected to handle more than this)
  - Up to 7000 m/s speed
  - 1 Hz navigation solution update

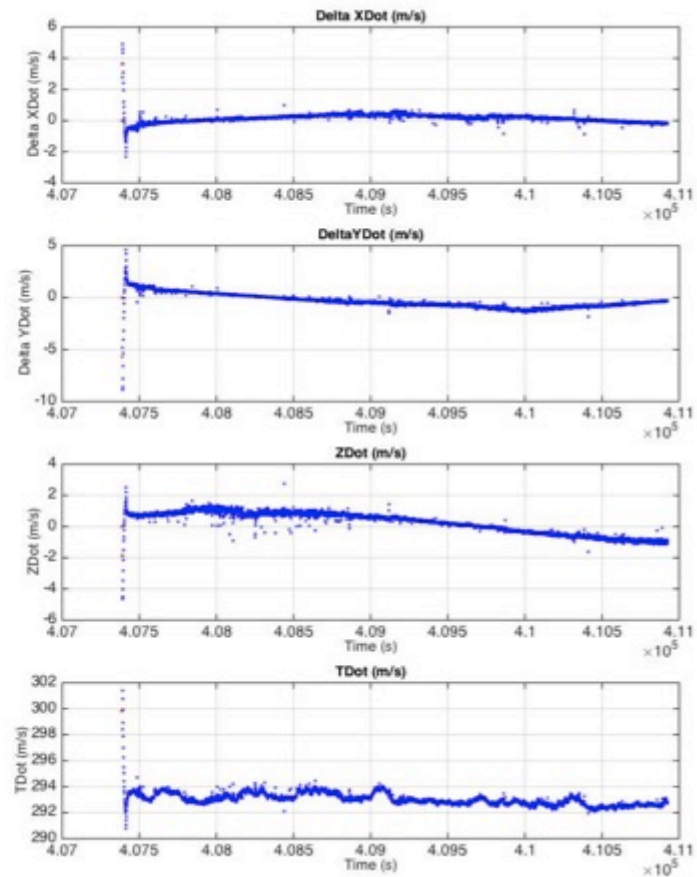
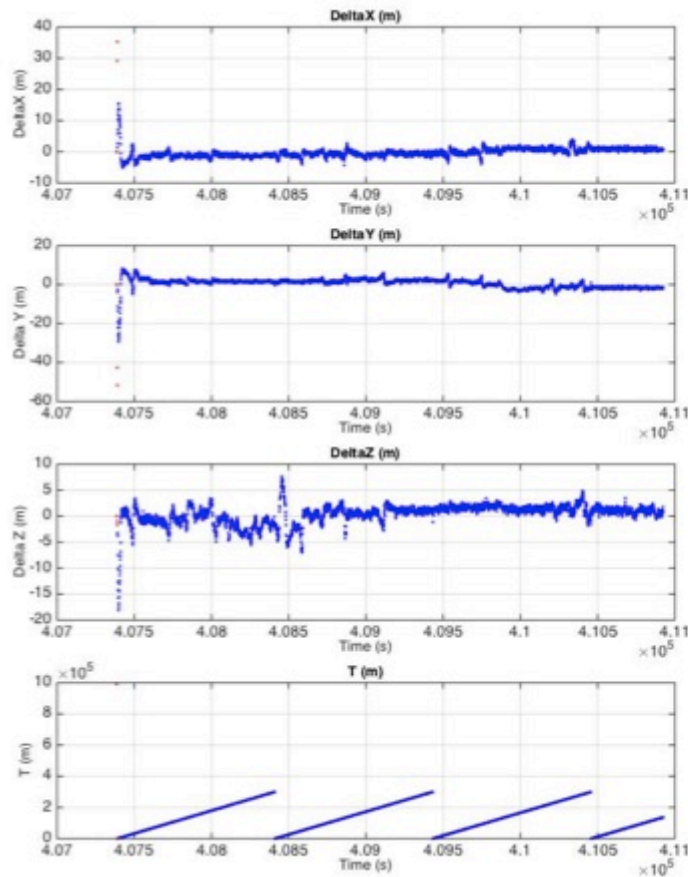


Namuru V32R3A testing



# Low Earth Orbit (LEO) Accuracy 1

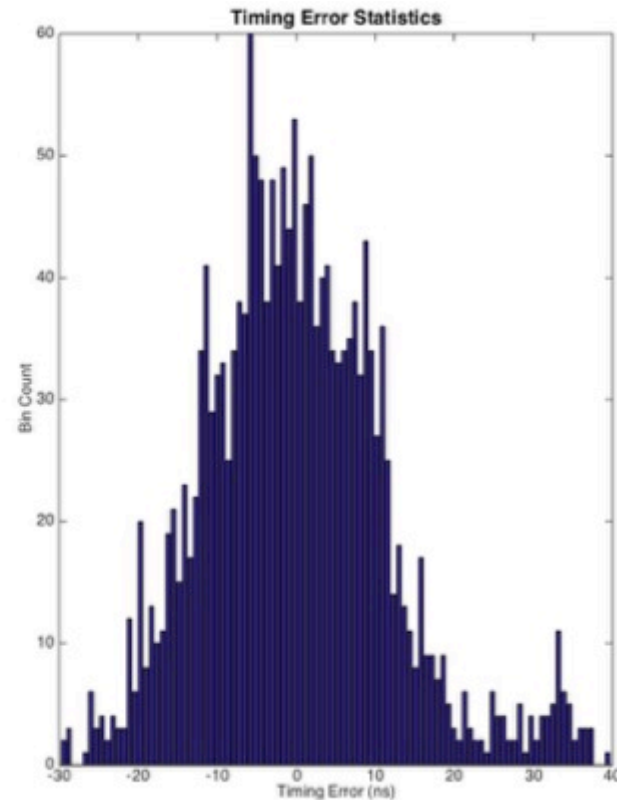
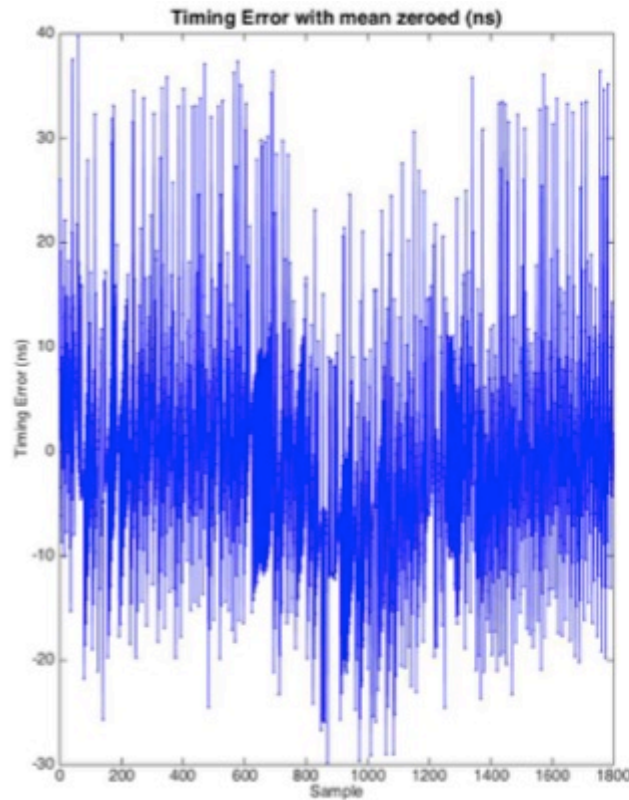
- Accuracy of low earth orbit test with Spirent GPS simulator (no ionospheric errors)



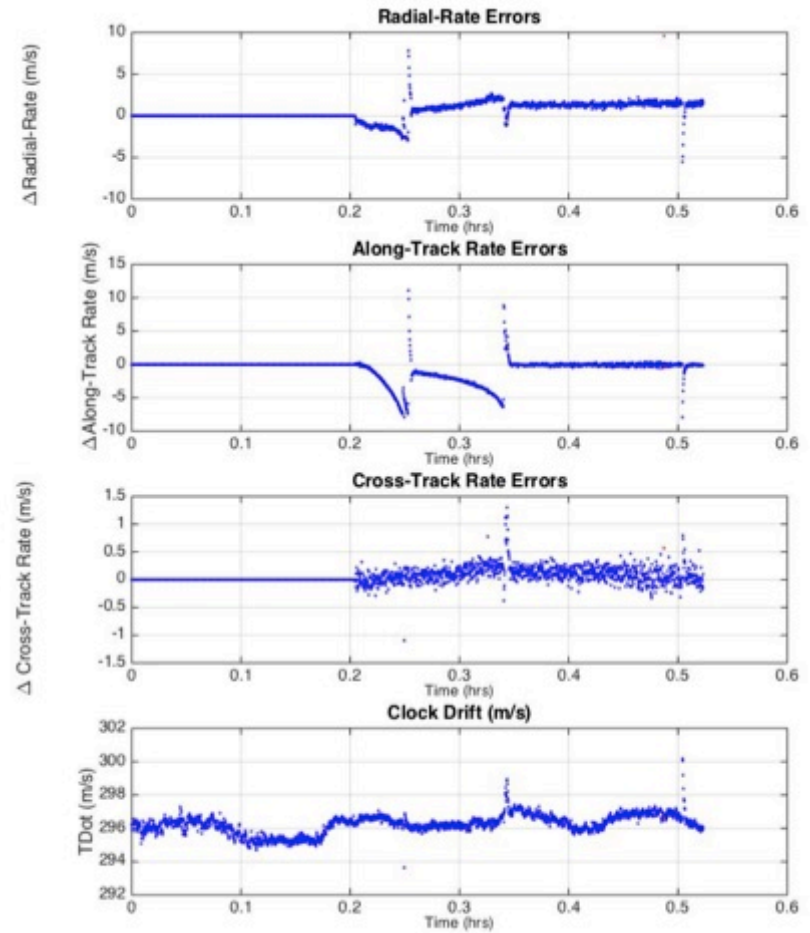
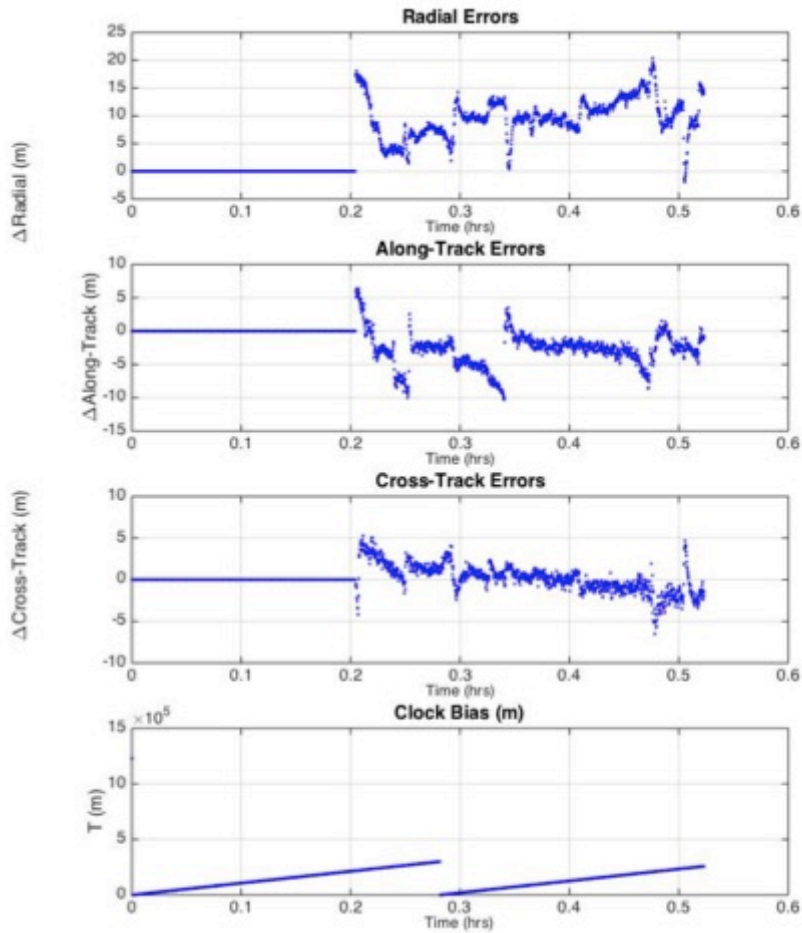
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# Timing Precision Test in LEO

- 1PPS timing precision tested with Spirent simulator



# Rocket: Radial/Along/Cross Track Errors



# Summary

- An Australian and New Zealand developed GPS receiver is available for cubesat and launch applications
- Design can be customized for different applications
- For more information, contact Mr Kevin Parkinson, Dr Eamonn Glennon, or Prof Andrew Dempster via the email addresses below or talk to us during the tea break
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